## Numerical Hydrodynamics

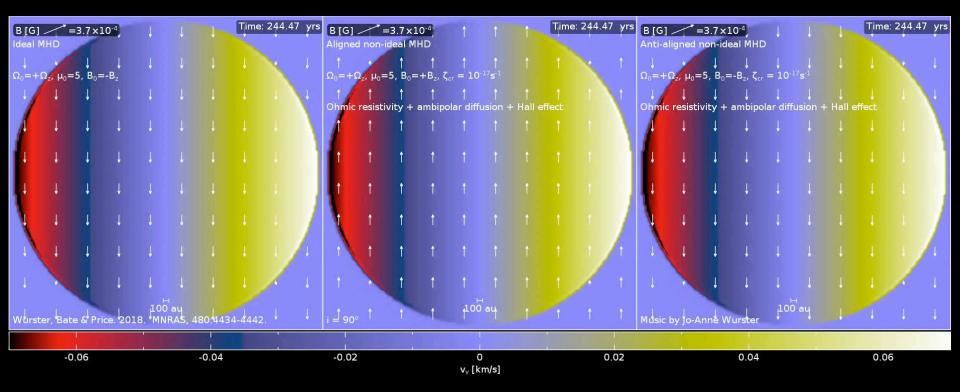
James Wurster

Fluids: PH4031

15 February 2021



### **Example:** Astrophysics: Star formation





### **Example:** Engineering

Wave on Oil Rig:

#### Urban Flooding:



https://www.youtube.com/watch?v=B8mP9E75D08

https://www.youtube.com/watch?v=jwz0stG4K9o



### **Example:** Movies!



The Day After Tomorrow (2004): <u>https://www.youtube.com/watch?v=GmjAp2eRDH0</u>

2 + 2 = 4 Simple Calculation

Fluid equations are often rate equations (e.g. the Parker wind model: equation for a spherically-symmetric, steady, isothermal outflow from a star of mass M\*):

$$\left(u^2 - c_s^2\right) \frac{1}{u} \frac{du}{dr} = \left(\frac{2c_s^2}{r} - \frac{GM_*}{r^2}\right)$$

> When possible, equations should be analytically simplified:

$$\bar{u}^2 - \ln(\bar{u}^2) - 4\ln(\bar{r}) - \frac{4}{\bar{r}} = K$$

- $\succ$  Although simplified, we still cannot analytically solve for u(r)
- > To solve u(r), numerical methods are required

# Simple Calculation: Using the Newton-Raphson Method

> The Newton-Raphson Method (commonly referred to as Newton's Method) is a very powerful tool to numerically find roots of an equation. In general, assume we are given an equation, f(x) = 0 and an initial guess for  $x = x_0$ . Then,

$$x_1 = x_0 - \frac{f(x_0)}{df(x_0)/dx}$$

 $\blacktriangleright$  Using the new  $x_1$ , we can repeat this method such that

$$x_2 = x_1 - \frac{f(x_1)}{df(x_1)/dx}$$

 $\succ$  and in general

$$x_{i+1} = x_i - \frac{f(x_i)}{df(x_i)/dx}$$

> This process is iterated until  $|x_{i+1}/x_i - 1| < \epsilon$ , where  $\epsilon$  is a pre-determined tolerance. The choice of  $x_0$  can be important; the closer to the actual value, the more stable the algorithm.

### Simple Calculation: Using the Newton-Raphson Method

Using a simple quadratic example:

$$f(x)=x^2-4=0$$

- > From inspection, we know the roots are  $x = \pm 2$
- Using Newton's method, the equation to iterate is

$$x_{i+1} = x_i - \frac{x_i^2 - 4}{2x_i}$$

→ Assuming initial guesses of  $x_0 = \pm 6$ 

$$x_{1} = 6.00 - \frac{6.00^{2} - 4}{2 \cdot 6.00} = 3.33$$
$$x_{2} = 3.33 - \frac{3.33^{2} - 4}{2 \cdot 3.33} = 2.27$$
$$x_{3} = 2.27 - \frac{2.27^{2} - 4}{2 \cdot 2.27} = 2.02$$
$$x_{4} = 2.02 - \frac{2.02^{2} - 4}{2 \cdot 2.02} = 2.00$$

$$x_{1} = -6.00 - \frac{-6.00^{2} - 4}{2 \cdot (-6.00)} = -3.33$$
$$x_{2} = -3.33 - \frac{3.33^{2} - 4}{2 \cdot (-3.33)} = -2.27$$
$$x_{3} = -2.27 - \frac{2.27^{2} - 4}{2 \cdot (-2.27)} = -2.02$$
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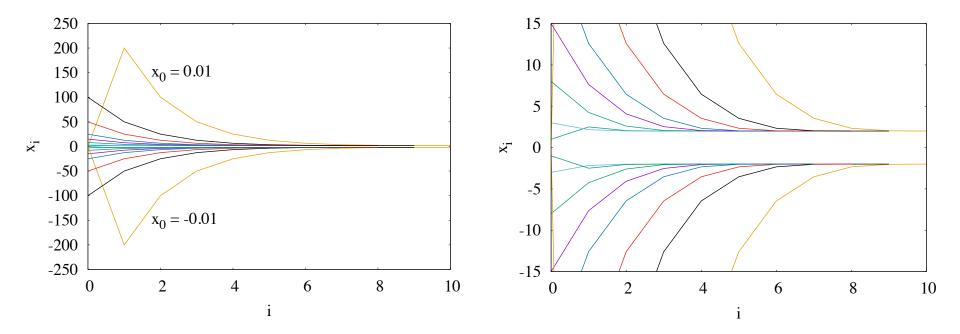
And we rapidly converge to  $x = \pm 2$ 

### Simple Calculation: Using the Newton-Raphson Method

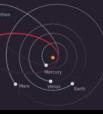
Using a simple quadratic example:

$$f(x)=x^2-4=0$$

- All  $x_0 > 0$  converge to x = +2 and all  $x_0 < 0$  converge to x = -2.
- Initial guess will determine how quickly the solution converges and to which root it converges (same plot, just different vertical scales)

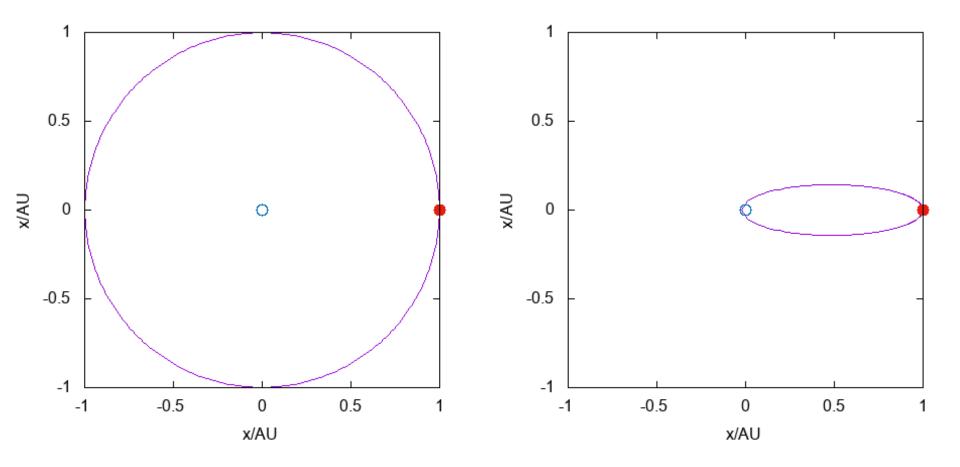


- This problem is a steady-state, and does not evolve in time
- > Although steady-state, this does represent the power of Numerical Methods



### **N-Body Calculation**

- Numerical methods are excellent at calculating N-body motion, such as planetary/cometary orbits (e.g. Exercise 3 in Computational Astrophysics)
- ▶ N-body calculations are integrated in time, and include gravity only but no fluid dynamics





### **Complex Calculation**

- Rather than a steady flow, or a gravity-only simulation, assume we have a dynamically evolving situation that includes fluids rather than discrete bodies (e.g. rolling clouds):
- > We do not have a single equation that can describe this motion
  - Motion cannot be described analytically
- > To solve this numerically, we require
  - > The initial properties of the system (i.e. initial conditions)
  - A method to divide the region (e.g. grids)
  - > A method to describe the edge of the region (i.e. boundary conditions)
  - A method to describe the evolution of the region
    - (i.e. the set of fluid dynamics equations)



Continuum Equations:

➤ Where

Continuity equation: 
$$\frac{D\rho}{Dt} = -\rho \nabla \cdot \boldsymbol{v}$$
  
Equation of motion:  $\frac{D\boldsymbol{v}}{Dt} = -\frac{1}{\rho} \nabla P$   
Energy equation:  $\frac{Du}{Dt} = -\frac{P}{\rho} \nabla \cdot \boldsymbol{v}$   
Equation of state:  $P = (\gamma - 1) \rho u$   
 $\frac{D}{Dt} = \frac{\partial}{\partial t} + \boldsymbol{v} \cdot \nabla$ 

is the Lagrangian (or co-moving) derivative



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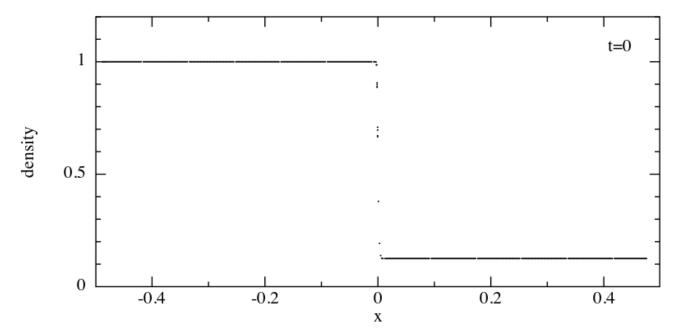
➢ Where

$$\frac{\mathrm{D}}{\mathrm{Dt}} \equiv \frac{\partial}{\partial t} + \boldsymbol{v} \cdot \boldsymbol{\nabla}$$

- > This is a closed set of equations: 4 equations 4 four unknowns
- ➤ The system evolves in time (i.e.  $\partial / \partial t$ ) & position i.e. ( $\nabla$ )
- > To convert to numerical equations, must first choose a grid



➤ Assume we have a simple 1D problem where the density is as follows:

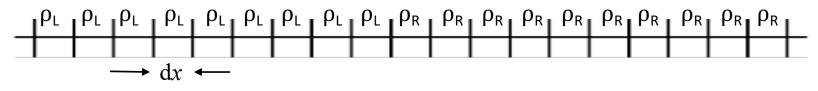


➢ How do we divide up the region?

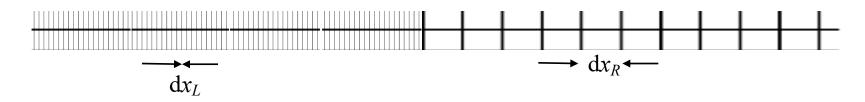


Eulerian grid:

grid of constant spacing, density varies in each cell

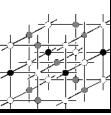


Lagrangian grid:
 grid of varying spacing, mass is constant



 Smoothed Particle Hydrodynamics:
 Spheres of constant mass represent 'packets' of fluid; density is dependent on proximity of neighbours

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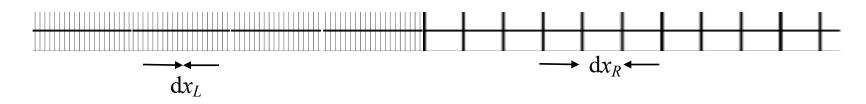


### Defining your problem: Dividing your region

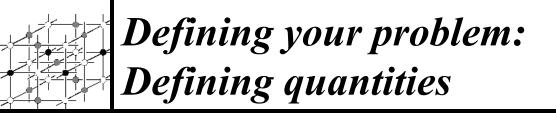
For Lagrangian systems, the co-moving derivative is simply

$$\frac{\mathrm{D}}{\mathrm{Dt}} \equiv \frac{\partial}{\partial t}$$

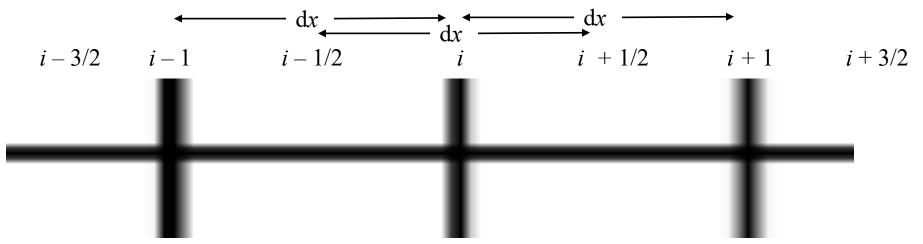
Lagrangian grid:
 grid of varying spacing, mass is constant



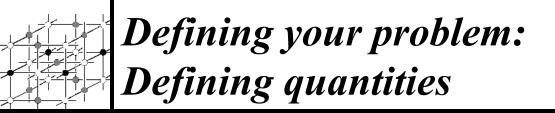
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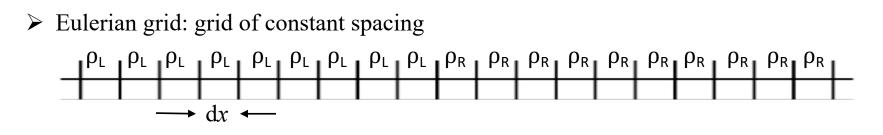


- $\succ \text{Eulerian grid: grid of constant spacing}$   $\downarrow \rho_{L} \rho_{L} \rho_{L} \rho_{L} \rho_{L} \rho_{L} \rho_{L} \rho_{L} \rho_{L} \rho_{R} \rho_{$
- $\succ$  A few cells:

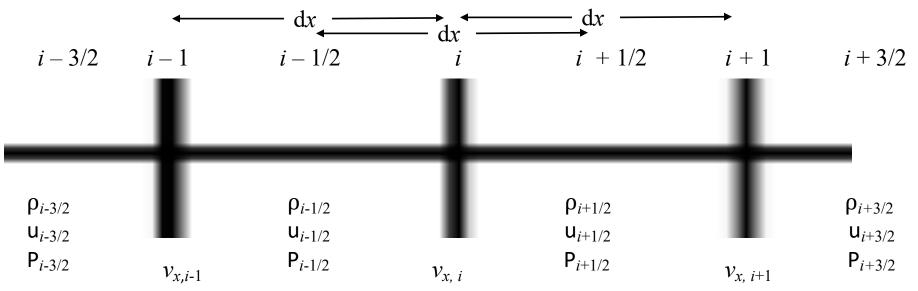


- > Quantities need to be defined at a given position.
  - Scalars: density, internal energy, pressure
  - Vectors: velocity





 $\succ$  A few cells:



- Scalars are calculated at *cell-centre*
- Vectors are calculated at *cell-interface*



### Complex Calculation: Required Components

➤ To solve any system numerically, we require

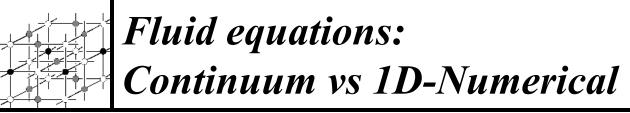
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$$\frac{\mathrm{D}\rho}{\mathrm{D}t} = -\rho\nabla \cdot \boldsymbol{v}$$
$$\frac{\partial\rho}{\partial t} + \boldsymbol{v} \cdot \boldsymbol{\nabla}\rho = -\rho\nabla \cdot \boldsymbol{v}$$

$$\frac{\partial \rho}{\partial t} = -\rho \nabla \cdot \boldsymbol{v} - \boldsymbol{v} \cdot \boldsymbol{\nabla} 
ho$$

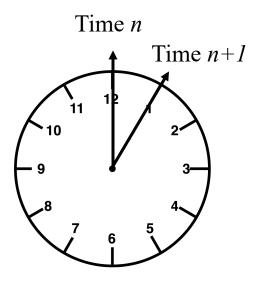


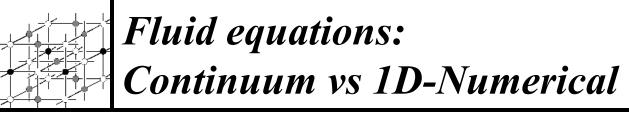
 $\frac{\partial \rho}{\partial t}$ 

$$\frac{\mathrm{D}\rho}{\mathrm{D}t} = -\rho\nabla\cdot\boldsymbol{v}$$
$$+\boldsymbol{v}\cdot\boldsymbol{\nabla}\rho = -\rho\nabla\cdot\boldsymbol{v}$$

$$\frac{\partial \rho}{\partial t} = -\rho \nabla \cdot \boldsymbol{v} - \boldsymbol{v} \cdot \boldsymbol{\nabla} \rho$$

$$\frac{\rho_{i+\frac{1}{2}}^{n+1} - \rho_{i+\frac{1}{2}}^n}{dt} = -\rho \nabla \cdot \boldsymbol{v} - \boldsymbol{v} \cdot \boldsymbol{\nabla} \rho$$





1 1

$$\frac{\mathrm{D}\rho}{\mathrm{D}t} = -\rho\nabla\cdot\mathbf{v}$$

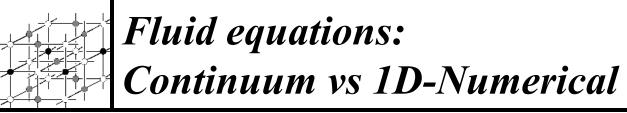
$$\frac{\partial\rho}{\partial t} + \mathbf{v}\cdot\nabla\rho = -\rho\nabla\cdot\mathbf{v}$$

$$\frac{\partial\rho}{\partial t} = -\rho\nabla\cdot\mathbf{v} - \mathbf{v}\cdot\nabla\rho$$

$$\rho_{i-1/2} \qquad \mathbf{v}_{x,i} \qquad \rho_{i+1/2} \qquad \mathbf{v}_{x,i+1} \qquad \rho_{i+3/2}$$

$$rac{
ho_{i+rac{1}{2}}^{n+1}-
ho_{i+rac{1}{2}}^n}{dt} \hspace{.1in} = \hspace{.1in} -
ho 
abla \cdot oldsymbol{v} - oldsymbol{v} \cdot oldsymbol{
abla} 
ho$$

$$\frac{\rho_{i+\frac{1}{2}}^{n+1} - \rho_{i+\frac{1}{2}}^{n}}{dt} = -\rho_{i+\frac{1}{2}}^{n} \frac{v_{x,i+1}^{n} - v_{x,i}^{n}}{dx} - \boldsymbol{v} \cdot \boldsymbol{\nabla}\rho$$



$$\frac{\mathrm{D}\rho}{\mathrm{D}t} = -\rho\nabla\cdot\mathbf{v}$$

$$\frac{\partial\rho}{\partial t} + \mathbf{v}\cdot\nabla\rho = -\rho\nabla\cdot\mathbf{v}$$

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$$\frac{\partial\rho}{\partial t} = -\rho\nabla\cdot\mathbf{v} - \mathbf{v}\cdot\nabla\rho$$

$$\frac{\rho_{i-1/2}}{\mathrm{d}x} = \frac{\nabla_{x,i}}{\mathrm{d}x}$$

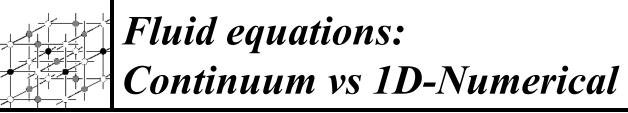
$$\frac{\rho_{i+1/2}}{\mathrm{d}x} = \frac{\nabla_{x,i+1}}{\mathrm{d}x}$$

$$\frac{\rho_{i+\frac{1}{2}} - \rho_{i+\frac{1}{2}}}{dt} = -\rho \nabla \cdot \boldsymbol{v} - \boldsymbol{v} \cdot \boldsymbol{\nabla} \rho$$

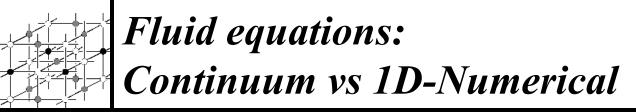
$$\frac{\rho_{i+\frac{1}{2}}^{n+1} - \rho_{i+\frac{1}{2}}^{n}}{dt} = -\rho_{i+\frac{1}{2}}^{n} \frac{v_{x,i+1}^{n} - v_{x,i}^{n}}{dx} - \boldsymbol{v} \cdot \boldsymbol{\nabla}\rho$$

$$\frac{\rho_{i+\frac{1}{2}}^{n+1} - \rho_{i+\frac{1}{2}}^{n}}{dt} = -\rho_{i+\frac{1}{2}}^{n} \frac{v_{x,i+1}^{n} - v_{x,i}^{n}}{dx} - \frac{v_{x,i+1}^{n} + v_{x,i}^{n}}{2} \frac{\rho_{i+\frac{3}{2}}^{n} - \rho_{i-\frac{1}{2}}^{n}}{2dx}$$

'zero-th order' approximation



$$\begin{array}{rcl} \frac{\mathrm{D}\rho}{\mathrm{D}t} &=& -\rho\nabla\cdot v \\ \frac{\partial\rho}{\partial t} &=& -\rho\nabla\cdot v \\ \frac{\partial\rho}{\partial t} &=& -\rho\nabla\cdot v \\ \frac{\partial\rho}{\partial t} &=& -\rho\nabla\cdot v - v\cdot\nabla\rho \\ \hline \\ \frac{\partial\rho}{\partial t} &=& -\rho\nabla\cdot v - v\cdot\nabla\rho \\ \frac{\rho_{i+\frac{1}{2}}^{n+1} - \rho_{i+\frac{1}{2}}^{n}}{dt} &=& -\rho\nabla\cdot v - v\cdot\nabla\rho \\ \hline \\ \frac{\rho_{i+\frac{1}{2}}^{n+1} - \rho_{i+\frac{1}{2}}^{n}}{dt} &=& -\rho_{i+\frac{1}{2}}^{n}\frac{v_{x,i+1}^{n} - v_{x,i}^{n}}{dx} - v\cdot\nabla\rho \\ \hline \\ \frac{\rho_{i+\frac{1}{2}}^{n+1} - \rho_{i+\frac{1}{2}}^{n}}{dt} &=& -\rho_{i+\frac{1}{2}}^{n}\frac{v_{x,i+1}^{n} - v_{x,i}^{n}}{dx} - v\cdot\nabla\rho \\ \hline \\ \frac{\rho_{i+\frac{1}{2}}^{n+1} - \rho_{i+\frac{1}{2}}^{n}}{dt} &=& -\rho_{i+\frac{1}{2}}^{n}\frac{v_{x,i+1}^{n} - v_{x,i}^{n}}{dx} - \frac{v_{x,i+1}^{n} + v_{x,i}^{n}}{2} \begin{cases} \frac{\rho_{i+\frac{1}{2}}^{n} - \rho_{i+\frac{1}{2}}^{n}}{dx} & \text{for } \frac{1}{2}(v_{x,i+1}^{n} + v_{x,i}^{n}) > 0 \\ \frac{\rho_{i+\frac{1}{2}}^{n} - \rho_{i+\frac{1}{2}}^{n}}{dx} & \text{for } \frac{1}{2}(v_{x,i+1}^{n} + v_{x,i}^{n}) < 0 \end{cases} \end{array}$$



> The discrete fluid dynamic equations for an Eulerian grid:

$$\begin{split} \rho_{i+\frac{1}{2}}^{n+1} &= \rho_{i+\frac{1}{2}}^{n} - dt \left( \rho_{i+\frac{1}{2}}^{n} \frac{v_{x,i+1}^{n} - v_{x,i}^{n}}{dx} + \frac{v_{x,i+1}^{n} + v_{x,i}^{n}}{2} f(\rho) \right) \\ v_{x,i}^{n+1} &= v_{x,i}^{n} - dt \left( \frac{2}{\rho_{i+\frac{1}{2}}^{n} + \rho_{i-\frac{1}{2}}^{n}} \frac{P_{i+\frac{1}{2}}^{n} - P_{i-\frac{1}{2}}^{n}}{dx} + v_{x,i}^{n} f(v) \right) \\ u_{i+\frac{1}{2}}^{n+1} &= u_{i+\frac{1}{2}}^{n} - dt \left( \frac{P_{i+\frac{1}{2}}^{n} \frac{v_{x,i+1}^{n} - v_{x,i}^{n}}{dx} + \frac{v_{x,i+1}^{n} + v_{x,i}^{n}}{2} f(u) \right) \\ P_{i+\frac{1}{2}}^{n+1} &= (\gamma - 1) \rho_{i+\frac{1}{2}}^{n+1} u_{i+\frac{1}{2}}^{n+1} \end{split}$$

→ where  $f(a) = \nabla a$ , and can be 0<sup>th</sup> order, 1<sup>st</sup> order (Donor cell) or even higher order (e.g. 2<sup>nd</sup> order van Leer; 3<sup>rd</sup> order piecewise parabolic advection; etc...)



- Quantities are solved at different locations
- > Should quantities also be solved at different times, where n is the current timestep?
  - Leapfrog
    - ▶ Update vectors to n + 1/2

$$v_{x,i}^{n+\frac{1}{2}} = v_{x,i}^{n-\frac{1}{2}} - dt \left( \frac{2}{\rho_{i+\frac{1}{2}}^n + \rho_{i-\frac{1}{2}}^n} \frac{P_{i+\frac{1}{2}}^n - P_{i-\frac{1}{2}}^n}{dx} + v_{x,i}^{n-\frac{1}{2}}f(v) \right)$$

> Using updates vectors, update scalars to n+1

$$\rho_{i+\frac{1}{2}}^{n+1} = \rho_{i+\frac{1}{2}}^{n} - dt \left( \rho_{i+\frac{1}{2}}^{n} \frac{v_{x,i+1}^{n+\frac{1}{2}} - v_{x,i}^{n+\frac{1}{2}}}{dx} + \frac{v_{x,i+1}^{n+\frac{1}{2}} + v_{x,i}^{n+\frac{1}{2}}}{2} f(\rho) \right)$$

$$u_{i+\frac{1}{2}}^{n+1} = u_{i+\frac{1}{2}}^n - dt \left( \frac{P_{i+\frac{1}{2}}^n}{\rho_{i+\frac{1}{2}}^n} \frac{v_{x,i+1}^{n+\frac{1}{2}} - v_{x,i}^{n+\frac{1}{2}}}{dx} + \frac{v_{x,i+1}^{n+\frac{1}{2}} + v_{x,i}^{n+\frac{1}{2}}}{2} f(u) \right)$$

 $P_{i+\frac{1}{2}}^{n+1} = (\gamma - 1) \rho_{i+\frac{1}{2}}^{n+1} u_{i+\frac{1}{2}}^{n+1}$ 



- > There are several different time and spatial integration techniques
- The more advanced the technique...
  - ➤ the more accurate the result
  - ➤ the longer the computational time

# In numerical studies, the user must always balance accuracy with time!



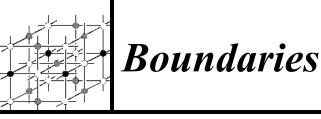


### Complex Calculation: Required Components

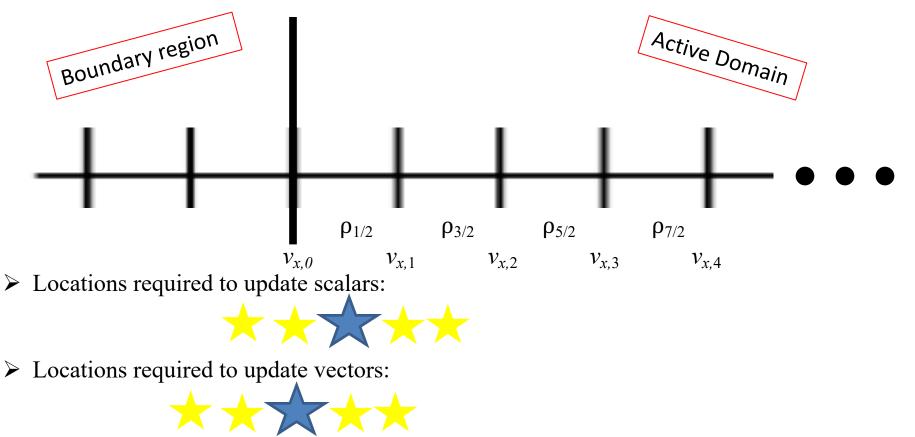
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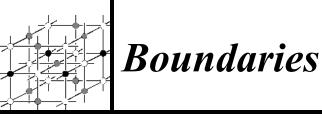
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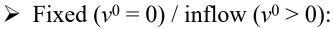
- We almost have enough information to run a simple simulation, but what happens at the edge of the simulation?
- Similar to solving differential equations, boundary conditions are required:

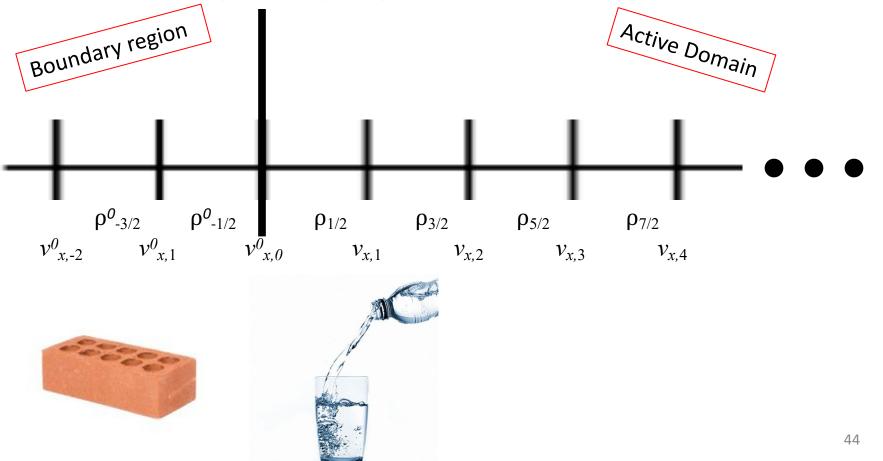


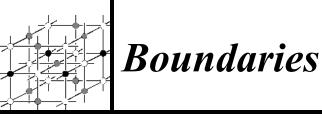


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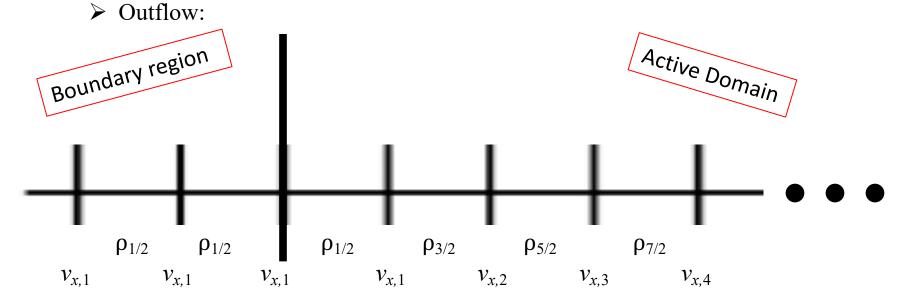




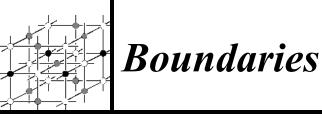


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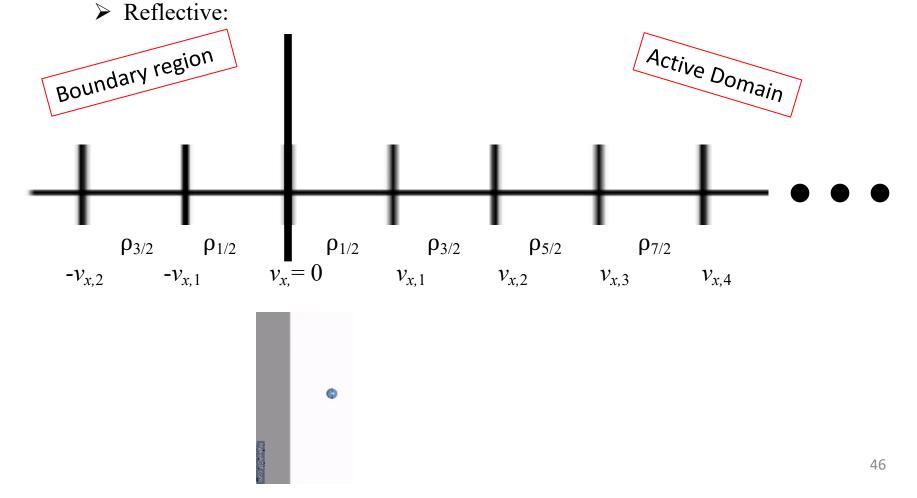
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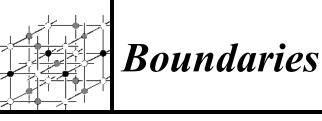




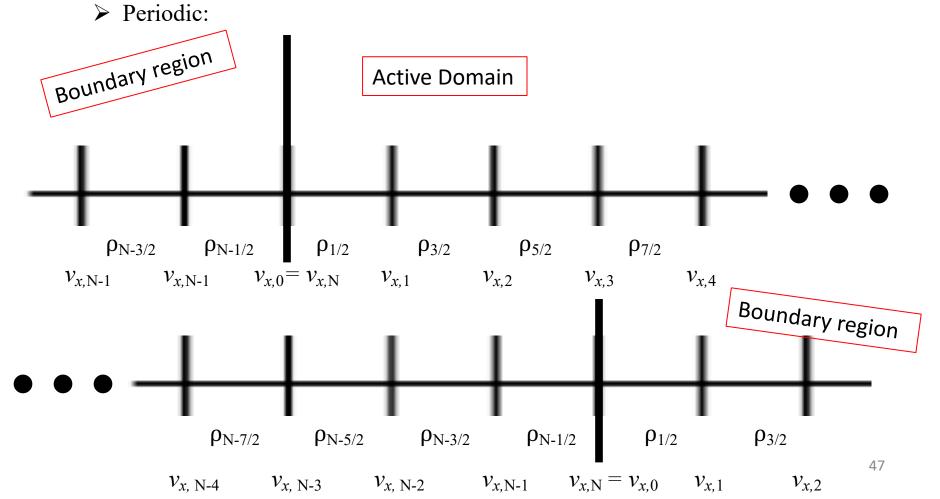


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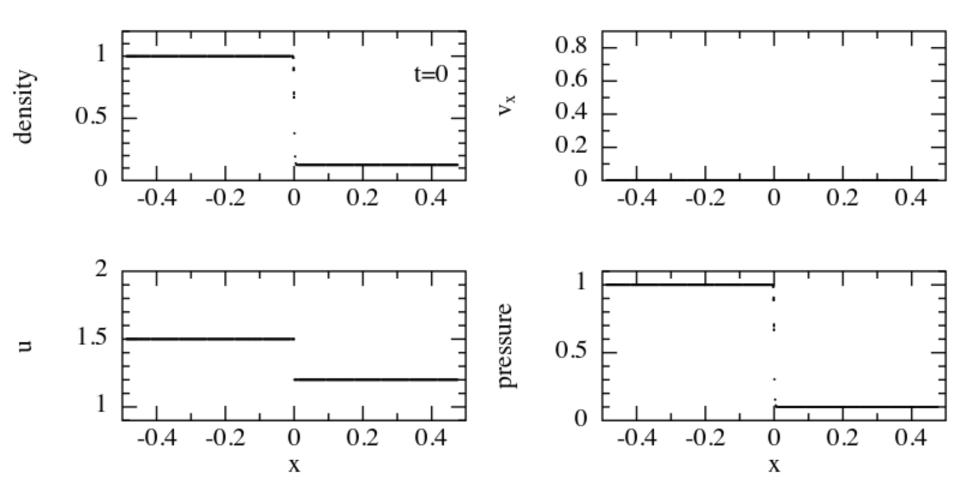
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- ➢ Initial conditions for the Sod Shock
- Boundary Conditions: fixed



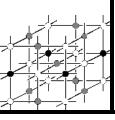


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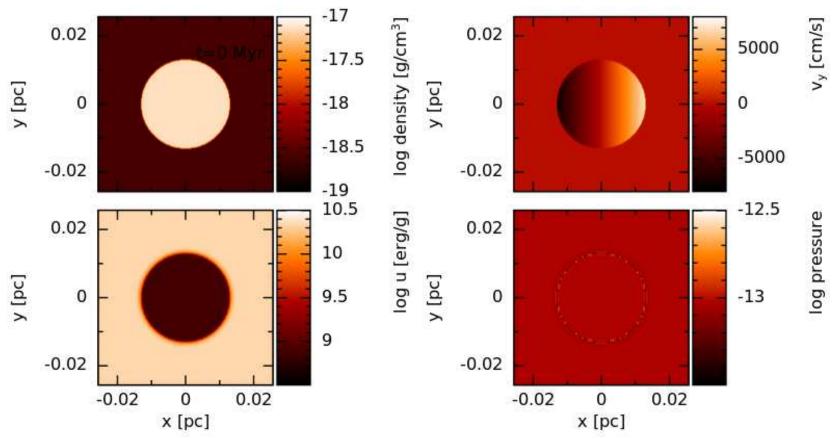
### Initial conditions:

### Astrophysical simulations

Initial conditions are incredibly important for any simulation

 A method to describe the evolution of the region: fluid dynamics equations
 A method to divide the region: smoothed particle hydrodynamics
 The initial properties of the system: see below

A method to describe the boundaries: sphere-in-box with periodic B.C.s





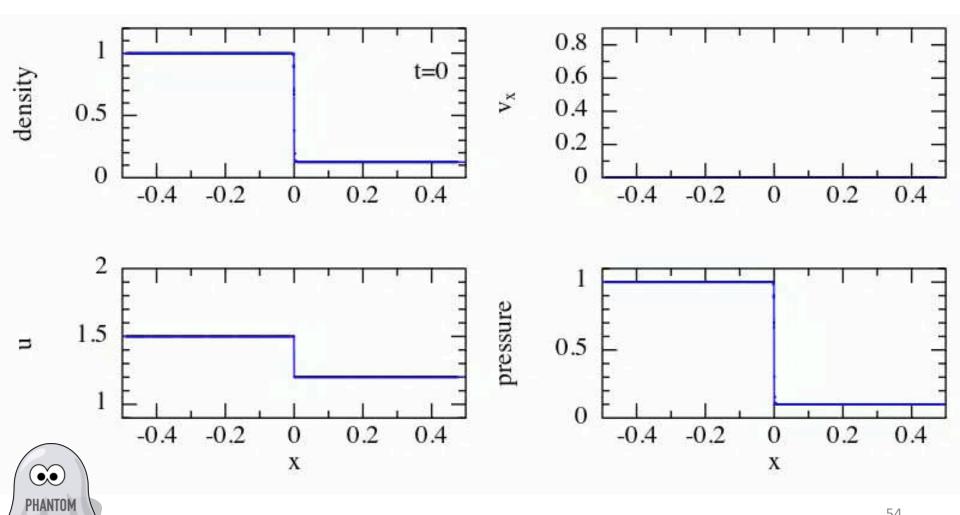
➤ Now that we have the basis of a code, can we now run complex physical calculations?

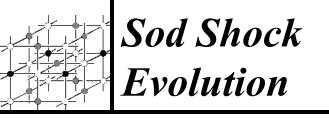


It must first be rigorously tested!

To test codes, we must run simple test problems where an analytical answer is known
 In numerical hydrodynamics, a common and simple test problem is the Sod Shock Tube (Sod 1978)







Ringing and instabilities occur at the shock wave and propagate backwards

